

#### Introduction

**TL;DR:** We rig <u>3D Gaussians</u> to a parametric mesh model (FLAME) for photorealistic head avatar creation and manipulation.

Fidelity: Using 3D Gaussian as the rendering primitive, we capture fine details like hair strands and eyelashes.

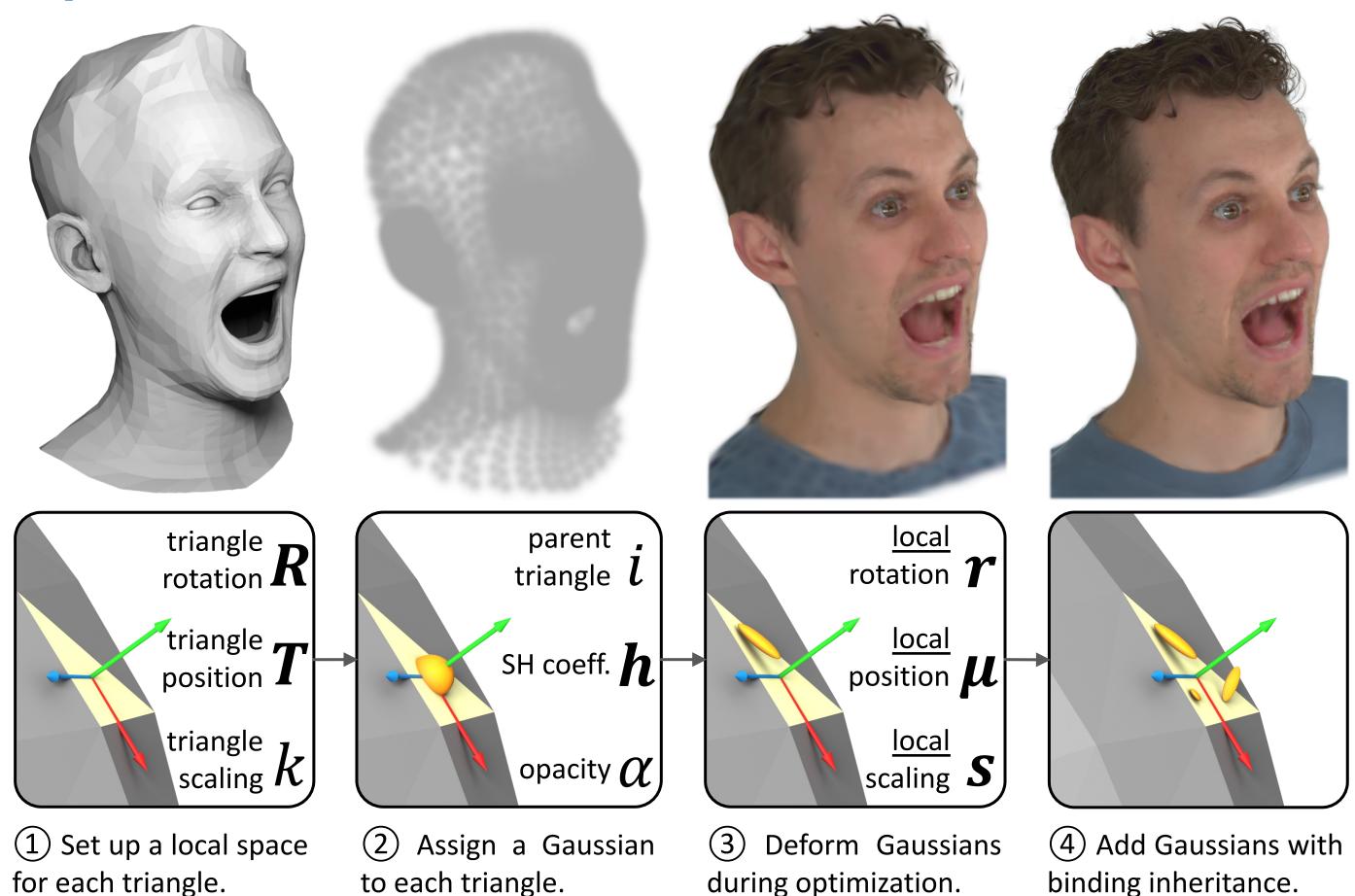
**Controllability:** We can manipulate Gaussian splats with FLAME as the control interface, independent of the number of splats.

**Connectivity:** The triangles implicitly bundle adjacent splats, enforcing smoothness on the movement of surrounding splats.



**Consistency:** A Gaussian splat is consistently attached to the same triangle during optimization. This enables effective finetuning of mesh parameters, drastically enhancing the reconstruction of visual details.

### Pipeline



Tobias Kirschstein<sup>1</sup> Shenhan Qian<sup>1</sup> Matthias Nießner<sup>1</sup> Liam Schoneveld<sup>2</sup> Davide Davoli<sup>3</sup> Simon Giebenhain<sup>1</sup> <sup>1</sup>Technical University of Munich <sup>2</sup>Woven by Toyota <sup>3</sup>Toyota Motor Europe NV/SA (associated partner by contracted service)

# GaussianAvatars: Photorealistic Head Avatars with Rigged 3D Gaussians

binding inheritance.

# Optimization

We optimize 3D Gaussian parameters from scratch and finetune FLAME's dynamic parameters with an RGB loss and two regularization terms.

FLAME p	3D Gau	
shape rtex offset	$\begin{bmatrix} \boldsymbol{\beta} \\ \boldsymbol{\Delta v} \end{bmatrix}$ static	<u>global</u> so <u>global</u> pos <u>global</u> rot
ranslation oint poses expression	$ \begin{bmatrix} t \\ \theta \\ \psi \end{bmatrix} dynamic $	parent tria SH coeffi op

#### ussian paramet

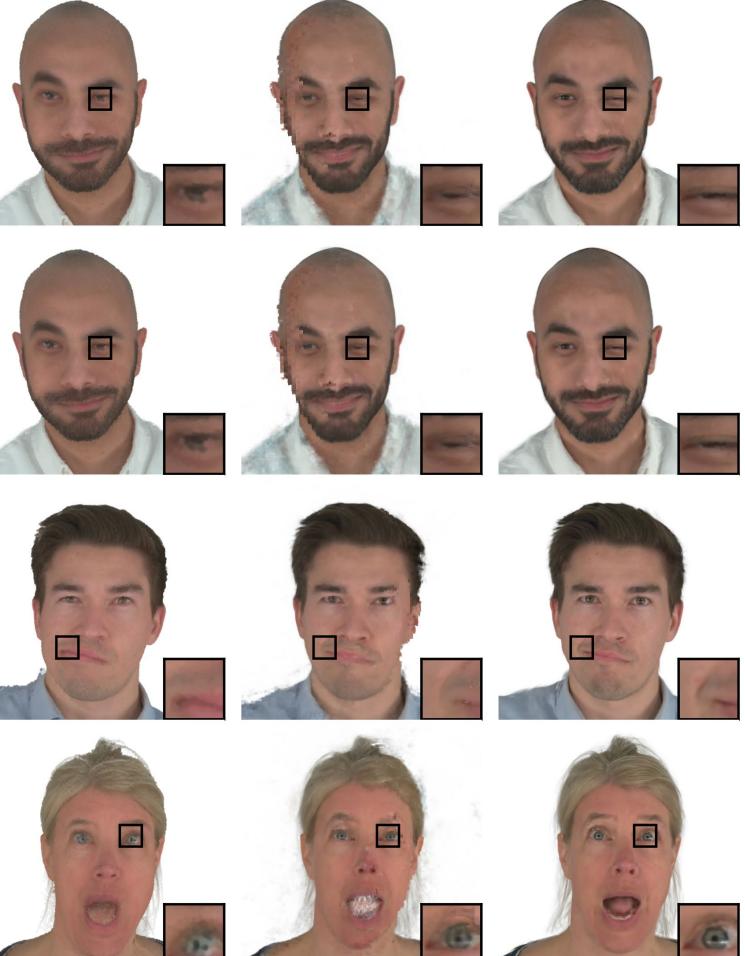
<u>global</u> scaling	s' = ks
<u>global</u> position	$\boldsymbol{\mu}' = k\boldsymbol{R}$
<u>global</u> rotation	r' = Rr
parent triangle	i
SH coefficient	h
opacity	α 🛹

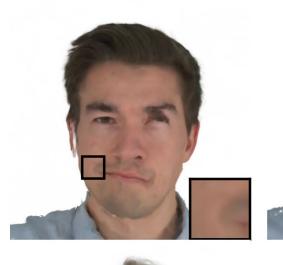
## Comparison

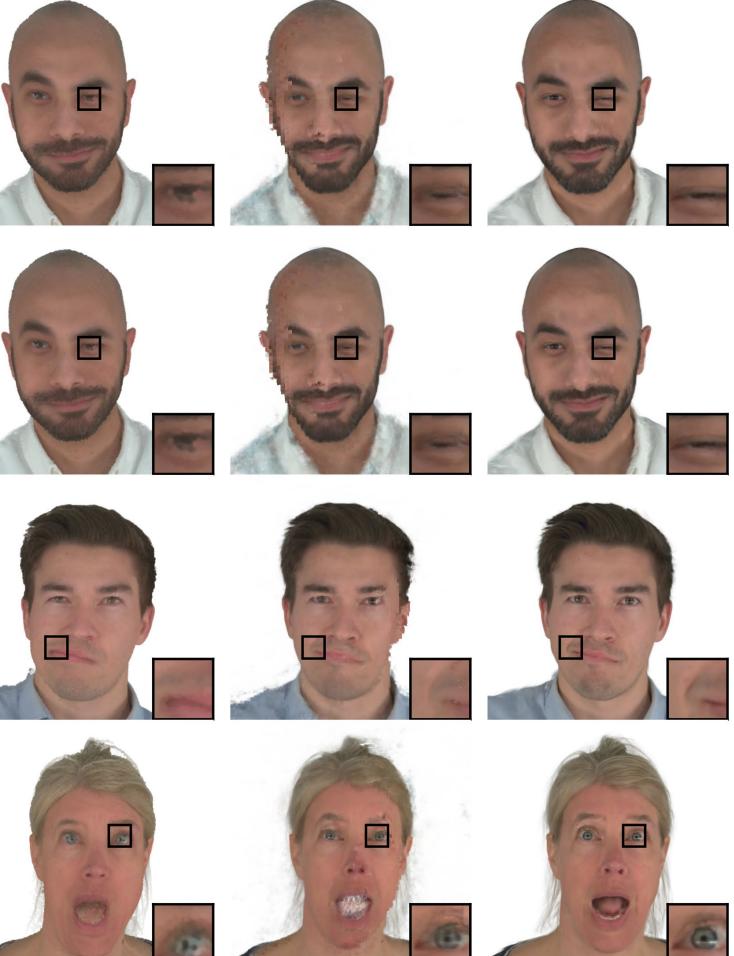
Novel-View Synthesis: render an avatar from a left-out viewpoint.

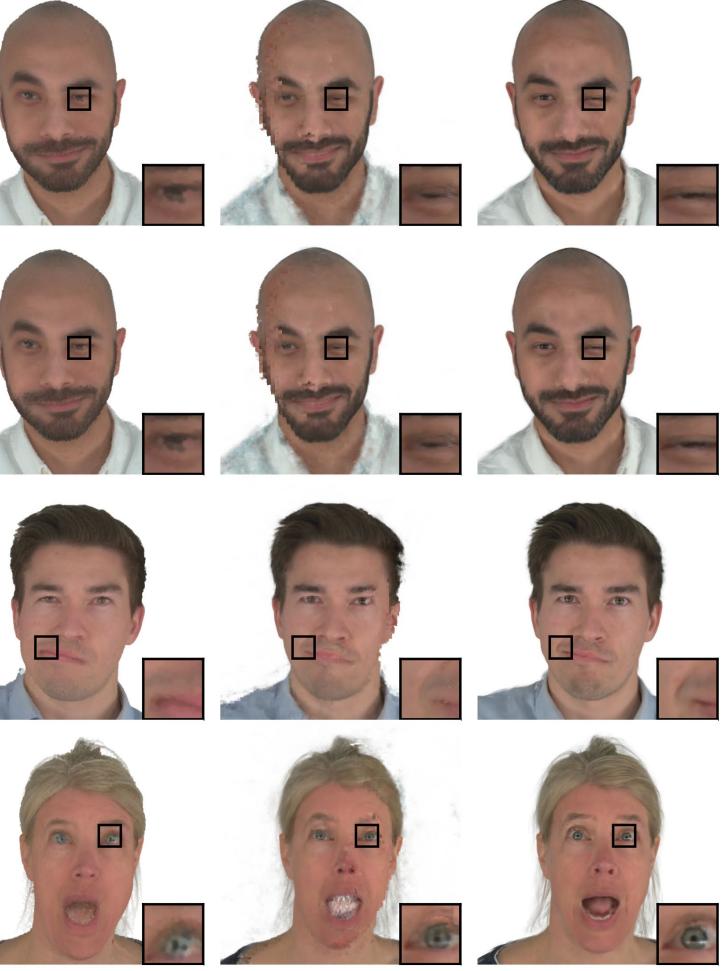
Self-Reenactment: animate an star with unseen expressions id poses from the same person.











Source Actor

AvatarMAV

PointAvatar

eters	loss terms
$R\mu + T$	$\mathcal{L}_{\rm rgb} = (1 - \lambda)\mathcal{L}_1 + \lambda\mathcal{L}_{\rm D-SSIM}$
	$\mathcal{L}_{\text{scaling}} = \left\  \max(\boldsymbol{s}, \ \epsilon_{\text{scaling}}) \right\ _{2}$ $\mathcal{L}_{\text{position}} = \left\  \max(\boldsymbol{\mu}, \ \epsilon_{\text{position}}) \right\ _{2}$

	Novel-View Synthesis				Self-Reenactment		
	PSNR↑	SSIM↑	LPIPS↓	<b>PSNR</b> ↑	SSIM↑	LPIPS↓	
AvatarMAV [47]	29.5	0.913	0.152	24.3	0.887	0.168	

INSTA

Ours

### Ablation and Visualization Regularizations prevent artifacts

# with novel expressions:

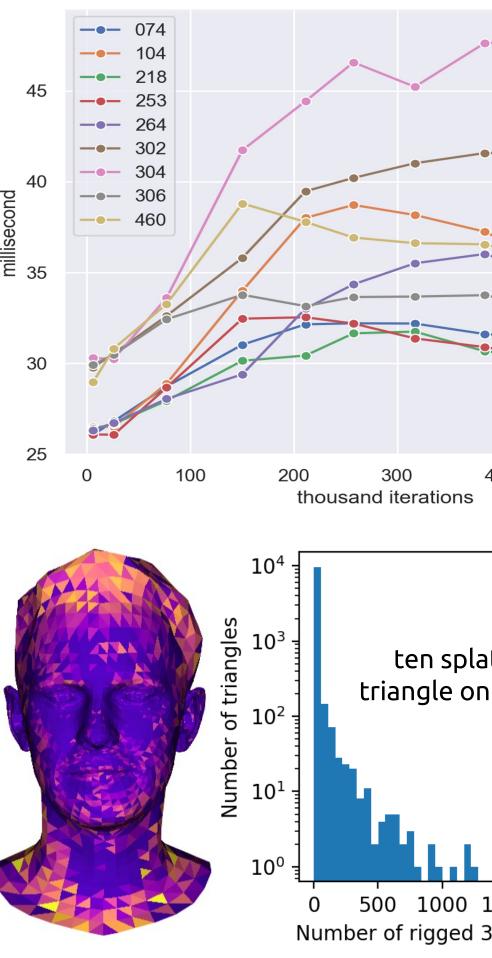
- A splat shouldn't be too far from its parent triangle.
- A splat shouldn't be too large on either axis. Smaller splats result in less blur.

#### FLAME parameter finetuning:

Fine-tuning FLAME parameters leads to more accurate mesh alignment to the input image. The movement of cheeks and lips is better captured with FLAME fine-tuning.

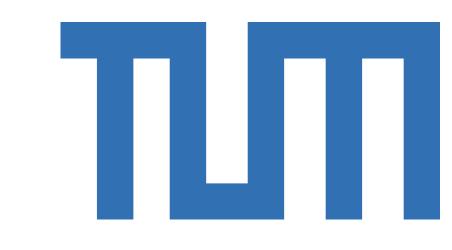
#### The number of Gaussians :

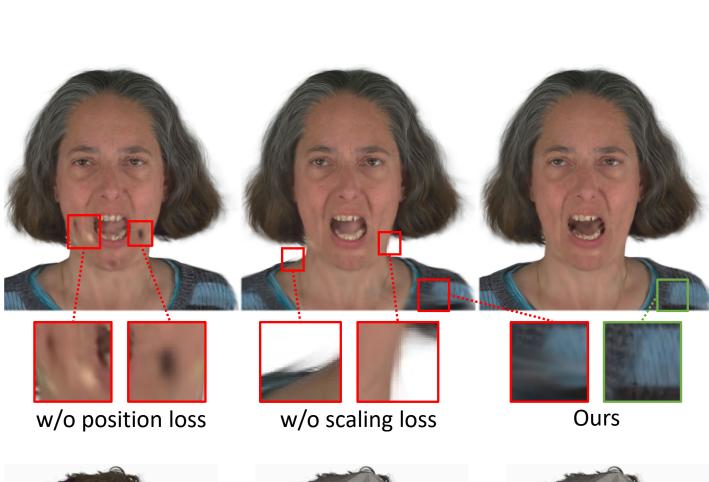
While the number of Gaussians grows by as much as 1000% during training, the run-time of each optimization iteration increases by less than 100%

















•	120			Resolution	FPS
	100				
•	oints 08			401×225	187
	thousand points 00 00		074 104	802×550	187
-•-	nort 40		218 253	1604×1100	156
•			264 302 304	3208×2200	95
	20	 	306 460	6416×4400	36
400 s		0 100 200 30 thousand			
		Novel-	View	Self-Reenactme	nt

		Novel-View			Self-Reenactment		
lats per		PSNR↑	SSIM↑	LPIPS↓	<b>PSNR</b> ↑	<b>SSIM</b> ↑	LPIPS↓
n average	Ours	28.8	0.883	0.098	25.1	0.853	0.101
	w/o ADC	26.8	0.854	0.206	25.1	0.860	0.183
	w/o $\mathcal{L}_{\text{scaling}}$	28.0	0.877	0.114	24.9	0.852	0.109
	w/o $\epsilon_{\text{scaling}}$	25.0	0.833	0.195	24.1	0.843	0.176
	w/o $\mathcal{L}_{\text{position}}$	29.7	0.894	0.091	24.9	0.851	0.096
	w/o $\epsilon_{\text{position}}$	28.7	0.882	0.105	25.0	0.855	0.106
1500 2000 3D Gaussians	w/o FLAME ft.	26.1	0.855	0.131	25.5	0.862	0.124